

Exploiting Dynamic Timing Slack for Energy Efficiency in Ultra-low-power Embedded Systems

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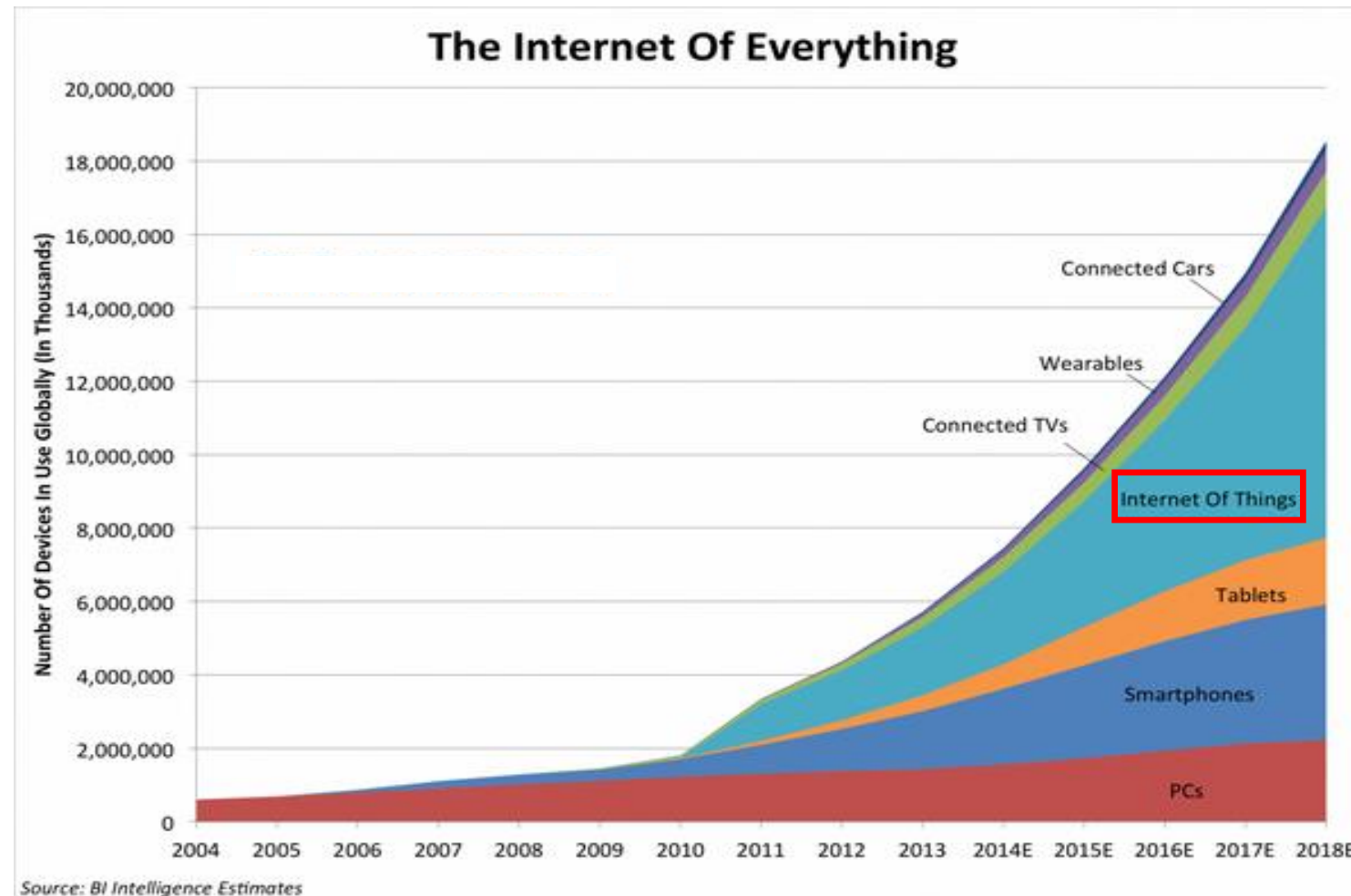
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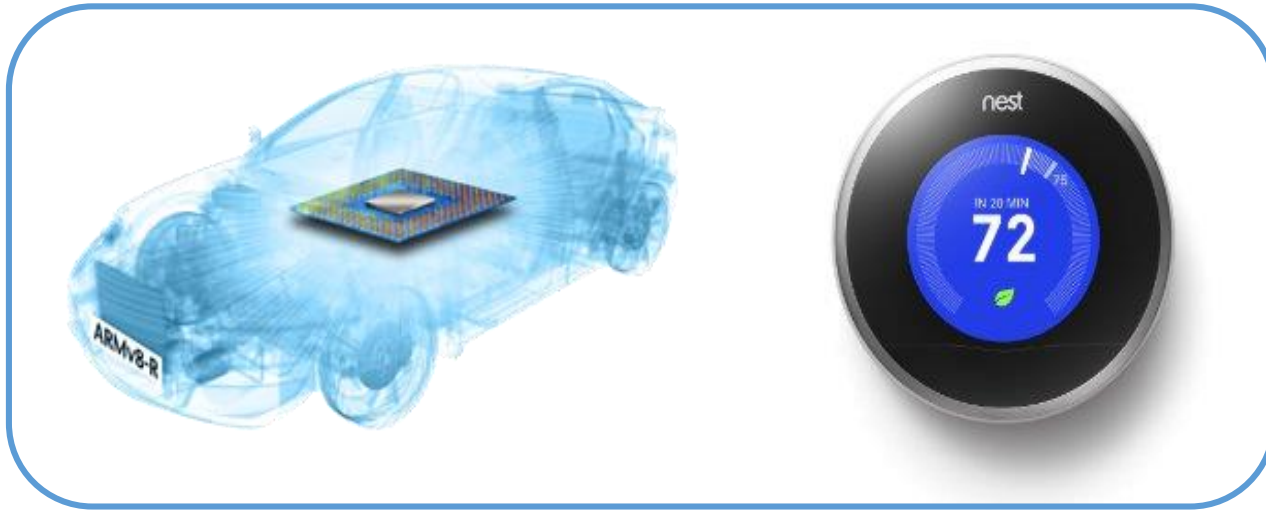


Why Ultra-low-power Embedded Systems?

- Low-power μ Ps and μ Cs are the **most abundant** type of processors
- Saving power for these processors can have a **huge impact**



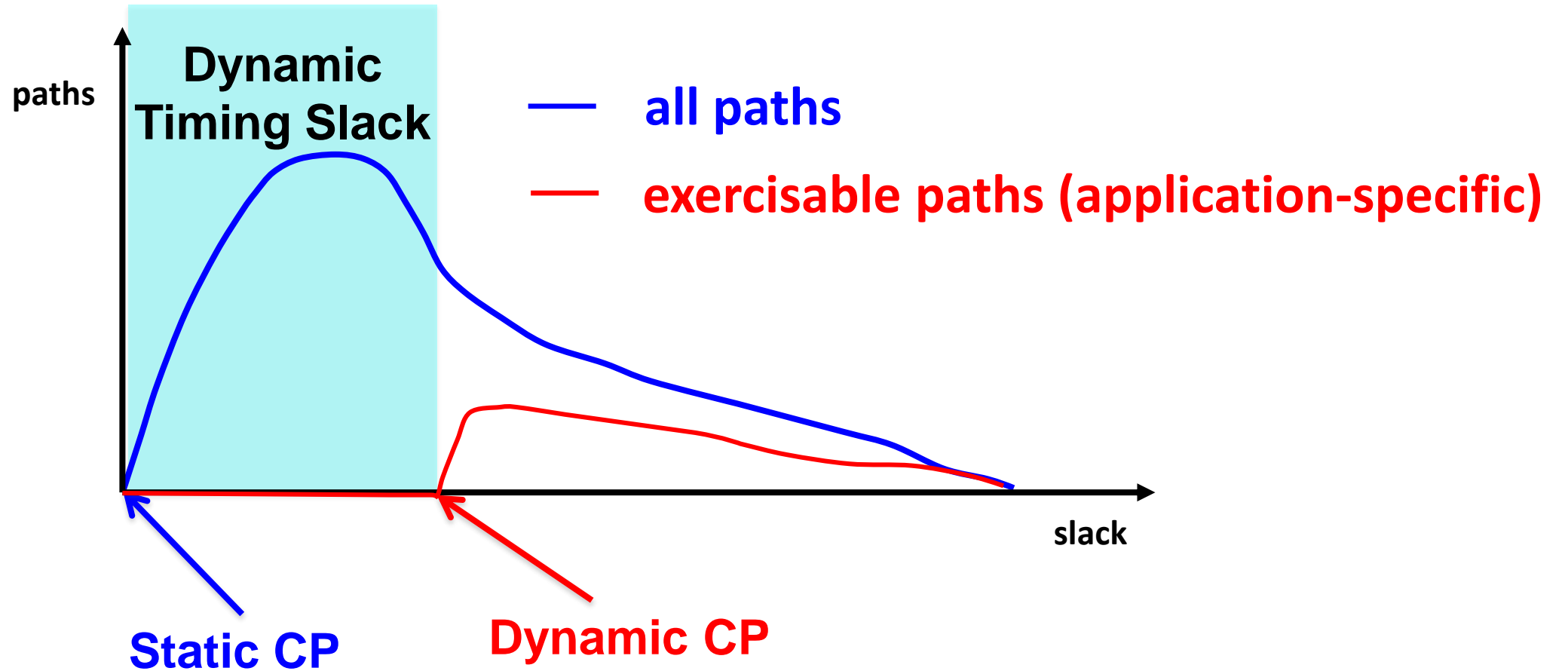
Opportunity



**Low-power
embedded systems
run same application
over and over**

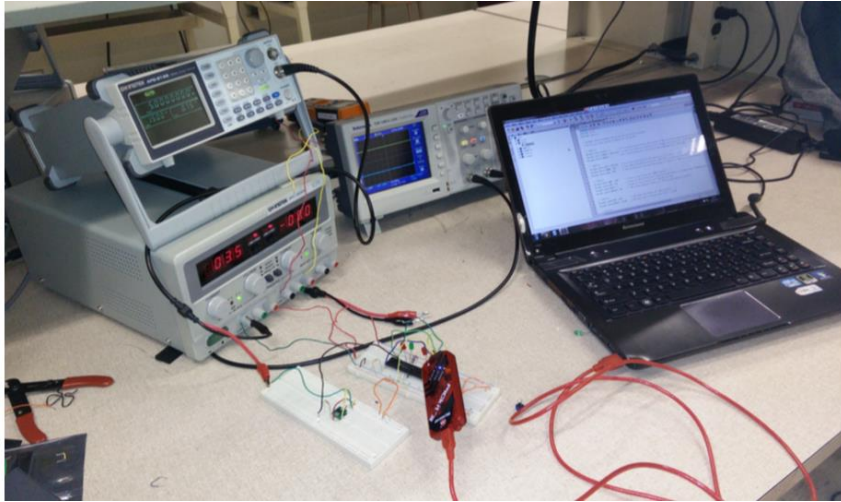
**Many applications do not exercise all functionalities
of a low power general purpose processor**

Dynamic Timing Slack (DTS)



**Reduce power (voltage) without
reducing performance (frequency)**

Dynamic Timing Slack: Fact or Fallacy?



Measurement setup

Benchmark	PIC24		MSP430	
	$V_{min}(V)$	Pwr Saved (%)	$V_{min}(V)$	Pwr Saved (%)
binSearch	1.82	20.2	2.87	30.3
div	1.83	20.3	2.87	33.7
inSort	1.85	17.2	2.90	36.2
intAVG	1.89	13.1	2.77	38.4
intFilt	1.83	20.0	2.92	30.5
mult	1.82	20.4	2.76	41.7
rle	1.77	25.5	2.83	35.9
tHold	1.83	20.1	2.86	34.4
tea8	1.82	20.4	2.82	39.5

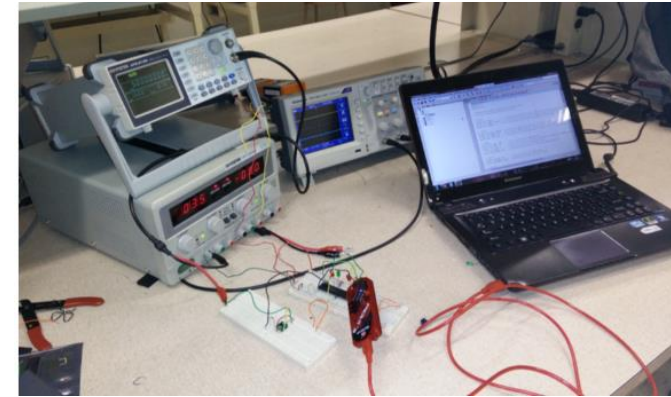
Measurements provide evidence of DTS
in real embedded systems

How to determine DTS?

Why not use input-based profiling?

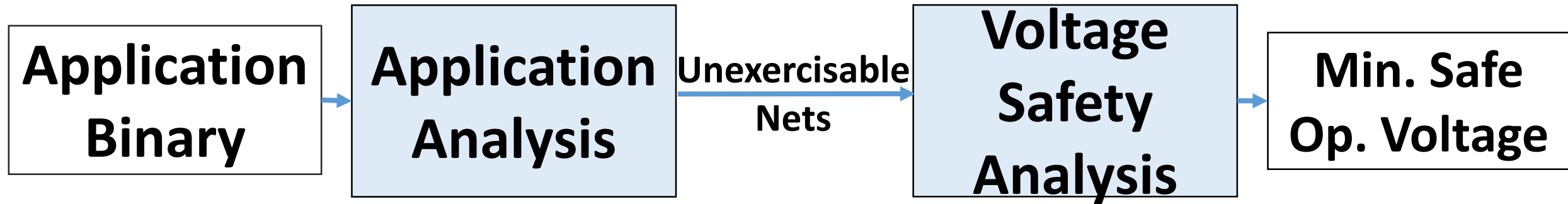
Problem:

- Activity depends on input
- Critical path can depend on input
- Variations depend on input and operating conditions



WE NEED A DIFFERENT APPROACH

Identifying Dynamic Timing Slack



**Symbolic simulation
with X as inputs for
input independent
analysis**

**Timing analysis at
worst case for
variation-independent
analysis**

Application Analysis

(Binary)

```
1.mov #0, r4;  
2.mov #0, r5;  
3.mov &0x0020, r15;  
4.cmp r15, #10000;  
5.jl else  
then:  
6.mov #1000, r4  
7.jump end  
else:  
8.mov #1000, r5  
end:  
9.sub r4, r5, r6;
```

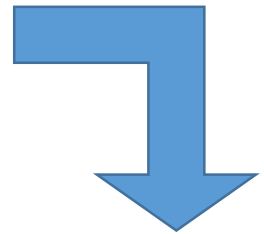
←X

```
1.mov #0, r4;  
2.mov #0, r5;  
3.mov &0x0020, r15;  
4.cmp r15, #10000;  
5.jl else
```

then:
6.mov #1000, r4
7.jump end

else:
8.mov #1000, r5

end:
9.sub r4, r5, r6;



**Unexercisable
Nets**

Voltage Safety Analysis

Unexercisable

Nets

$c \rightarrow 0$

$e \rightarrow 1$

Critical Paths

~~B-a-c-g-F~~

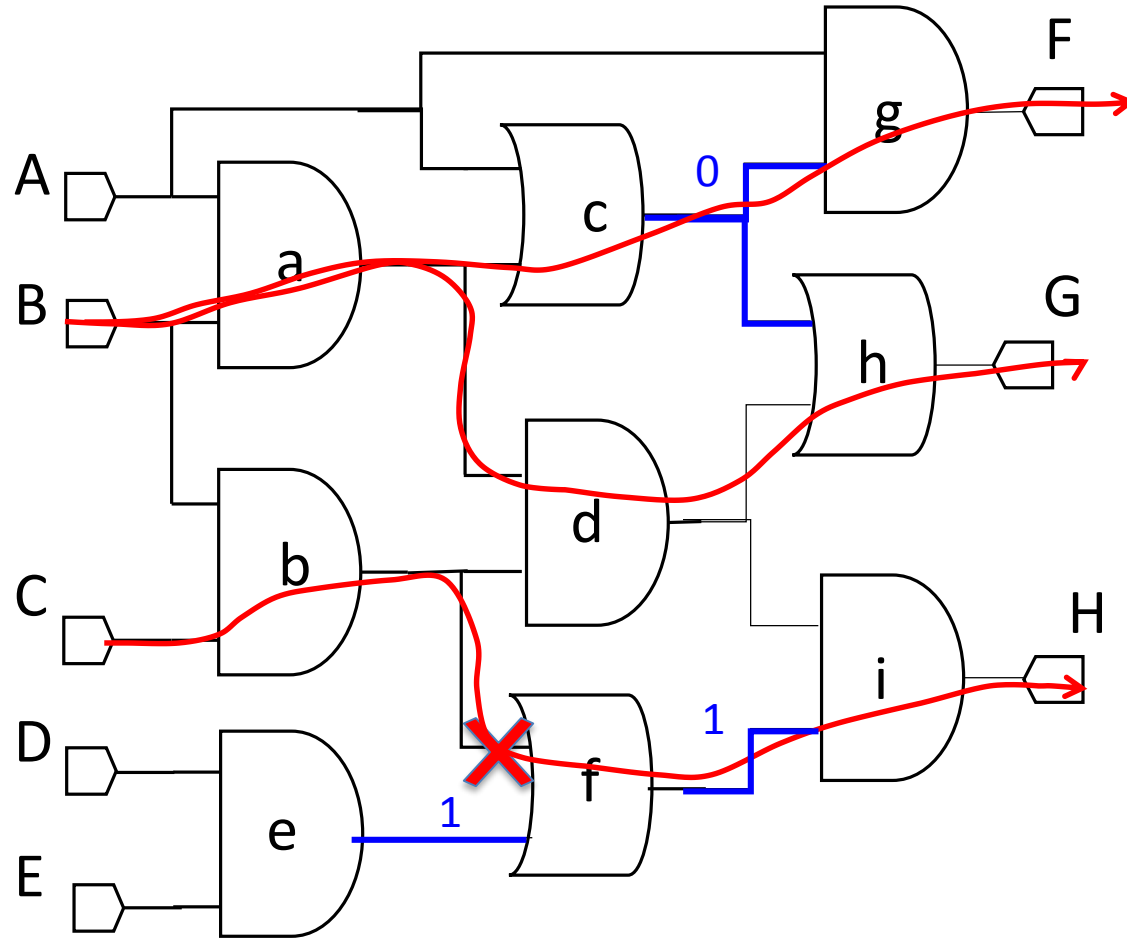
~~C-b-f-i-H~~

B-a-d-h-G

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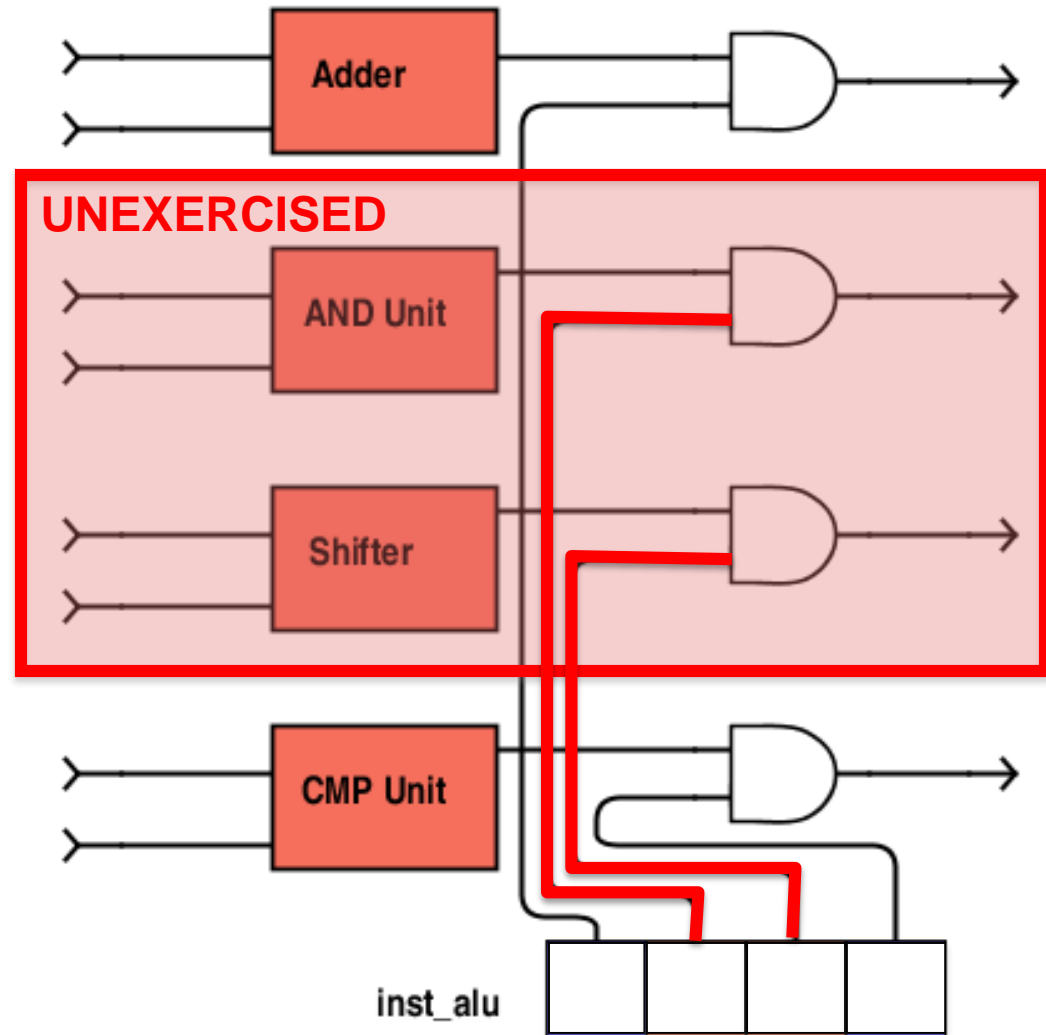


V_{min}

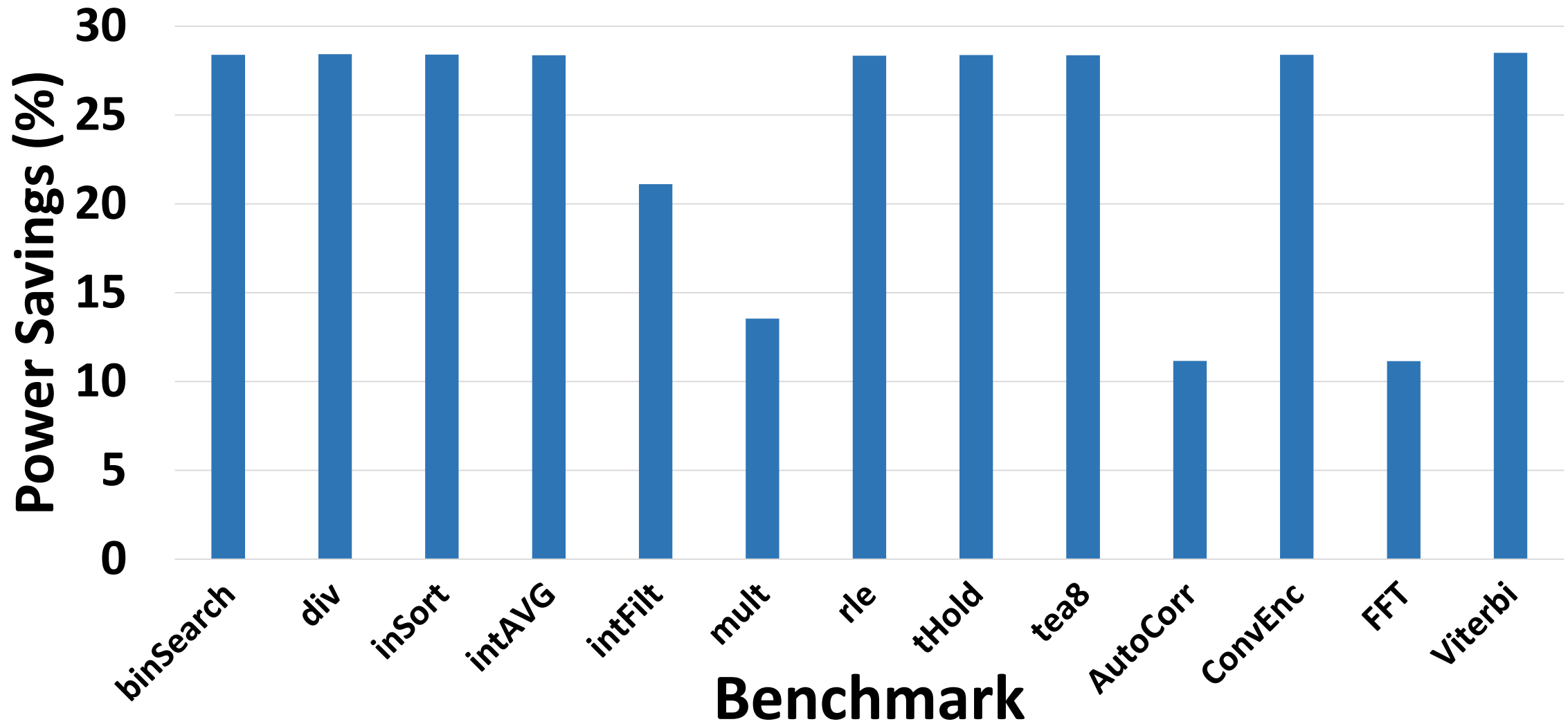
Real Example

example code block for tHold :

```
mov #0, r4 ; Initialize counter  
loop:  
mov &0x0020, r15 ; Read from mem/port  
cmp r15, #10000 ; Threshold Detection  
jl else  
then:  
inc r4  
mov r4, 0x0028 ; Write to mem/port  
else:  
jmp loop
```



Power savings from exploiting DTS



25% free power savings, on average

Conclusion

- Emerging applications are severely power constrained
- Only exercised parts of the processor need to meet timing
- Exploiting Dynamic Timing Slack can **reduce power without reducing performance**
- Average of **25%** free power/energy savings